How to download the new Isr file to drive ELD5-400

- 1. Pls download the lsr setting file to your laptop .
- 2. Open protuner like this below :

Leadshine ACHSeries (Offline)

Communication Display Tools Language Help

rameter Manage								×
ReadFile 💾 SaveAs	t Unload	Download Save Save	Paramete	rCompare 🎻 Reset	Hel	р		
Classify Select	Parameter N	ParameterName	Value	Range	Default	Units	Remark	4
	Pr7.00	Current loop gain	600	100 ~ 5000	2000	Hz	No	
ainAdiustment	Pr7.01	Current loop integral time	200	1~10000	20	0.1ms	No	
ibrationSuppression	Pr7.02	Motor rotor initial position Angl	330	0~360	0	-	Power off valid	
elocityTorqueControl	Pr7.03	Reserved parameter	0	0~32767	0	-	Power off valid	
onitorSetting rtensionSetting	Pr7.04	Reserved parameter	600	0~32767	0	-	Power off valid	
pecialSetting	Pr7.05	Motor pole pairs	4	1~20	4	-	Power off valid	
actorySetting	Pr7.06	Motor phase resistor	27	1~10000	100	0.01 Ω	Power off valid	
	Pr7.07	Motor D/Q inductance	130	1~10000	700	0.01mH	Power off valid	
	Pr7.08	Motor back EMF coefficient	92	100 ~ 10000	1000	0.1\/(100	Power off valid	
	Pr7.09	Motor torque coefficient	149	1~1000	80	0.01N.m/A	Power off valid	
	Pr7.10	Motor rated speed	3000	100 ~ 6000	2000	r/min	Power off valid	
	Pr7.11	Motor Maximum speed	5000	100 ~ 6000	2500	r/min	Power off valid	
	Pr7.12	Motor rated current	1201	1~3000	280	0.01A	Power off valid	
	Pr7.13	Motor rotor inertia	34	1 ~ 32767	250	0.01Kg.cm2	Power off valid	
	Pr7.14	Motor power selection	400	10 ~ 32767	750	W	Power off valid	
	Pr7.15	Motor model input	0	0 ~ 7FFF	3	-	Hexadecimal, power off v	alic
	Pr7.16	Encoder selection	36	0~512	0	-	Power off valid	
	Pr7.17	Motor maximum current	300	1~500	300	%	Power off valid	
	Pr7.18	Encoder Index Angle compen	150	0~360	0	-	No	
	Pr7.19	Reserved parameter	550	0~500	0	-	No	
	Pr7.20	Drive model input	0	FFFF8001 ~ 7FFF	0	-	Hexadecimal, power off	val
	Pr7.21	Servo model input	150	-32767 ~ 32767	0	-	Power off valid	
	Pr7.22	Reserved parameter	-185	-1000 ~ 1000	0	-	Power off valid	
	Pr7.23	Reserved parameter	0	-9000 ~ 9000	0	-	Power off valid	
	Pr7.24	Fan control mode setting	0	0~1	0	-	Power off valid	
Add Custom	1	- · · · ·	50	00.01.00	50	A =	B // P1	

3. Click "readfile" : , then find the file from your laptop like below :

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Communication Display Tools Language Help

Parameter Manage ReadFile SaveAs TUnload Download 🗱 Save 🎇 ParameterCompare 💣 Reset 🕞 Help	×
ReadFile BaveAs TUnload Download 🔤 Save 🎇 ParameterCompare 💞 Reset 🕞 Help	
Classify Select. Parameter N ParameterName Value Range Default Units Remark	
Pr7.00 Read parameter list X Hz No	A
GainAdjustment Pr7.01 0.1ms No	
VibrationSuppression Pr7.02 本地范围(0): ■ 电机配置参数	
MonitorSetting Pr7.03 Excelet(). Power off valid	
ExtensionSetting Pr7.04 - Power off valid	
Special Setting Pr7.05 名称 修改日期 类型 个 Power off Valid	
Pr7.06 Dr7.07 ACM604V48-T-2500.lsr 3/1/2019 9:16 PM LSR 文作 0.01mH Dever off valid	
Pr7.08 ACM604V60_T-2500 kr 3/27/2019 2:46 PM LSR 文化 0.1V//100 Power off valid	
Pr7.10 ACM604V60-1-2500_ELD5-400.lsr 3/27/2019 3:40 PM LSR X/ r/min Power off valid	
Pr7.11 ACM804V24HM-2500_PH 类型; LSR 文件 19 9:16 PM LSR 文作 Power off valid	
Pr7.12 ACM4005V24H-B5.lsr 大小: 2.56 KB 19 9:16 PM LSR 文化 0.01A Power off valid	
Pr7.13 Pr7.13 修改日期: 3/27/2019 3:40 PM 19 9:16 PM USB 文化 0.01Kg.cm2 Power off valid	
Pr7.14 Pr7.14 Prover off valid	
Pr7.15 Hexadecimal, power off vali	c
Pr7.16 – Power off valid	. 11
P7.17 文件名(N): ACM604V60-T-2500_ELD5-400 打开(O) % Power off valid	
Pr7.18	
Pr7.19 Pr7.20 文件类型(T): Isr Files(*.lsr) ▼ Prave HevedooimeL neworoffur	
Pr7.20 Prover off velid	
Pr7.22 Beserved parameter -185 -1000 Unit - Power off valid	
Pr7.23 Reserved parameter 0 -9000 00 - Power off valid	
Pr7.24 Fan control mode setting 0 0 0~1 0 - Power off valid	
Add Custom	Ľ.
Description:	%

4. Then click "download"

Leadshine ACHSeries (Offline)

Communication Display Tools Language Help

Add Custon Saved Image of the lange									
Classify Select Parameter N. Parameter Name Value Range Default Units Remark sicSetting indigitsment brationSuppression intorSetting ecisISetting ecisISetting Pr0.01 Control mode 20 20° 39 0 - Power of valid Pr0.02 Real-time auto-gain tuning mo. 2 0°2 0° - No Pr0.03 Selection of machine stiffness 70 50° 81 70 - No Pr0.04 Radio of inertia 250 0°11000 250 % No Pr0.05 Command pulse input selection 0 0°11 0 - No Pr0.05 Command pulse input selection 0 0°11 0 - No Pr0.07 Command pulse input mode s 0 0°32767 0 Pulse Power of valid Pr0.08 Commentor of electronic gear 1 1°32767 1 - No Pr0.10 Denominetor of electronic gear 1 1°32767 1 - No </th <th>ReadFile 💾 SaveAs</th> <th>1 Unload</th> <th>Download save Save</th> <th>Paramet</th> <th>erCompare 💣 Reset</th> <th>Hel</th> <th>р</th> <th> /</th> <th></th>	ReadFile 💾 SaveAs	1 Unload	Download save Save	Paramet	erCompare 💣 Reset	Hel	р	/	
Add Custom Mode loop gain 1 0 ~ 32767 1 0.11z No Add Custom Control mode 20 20 ~ 39 0 - No Pho10 Control mode 20 20 ~ 39 0 - No elocityTorqueControl onitorSetting Poil Selection of machine sittiness 70 50 ~ 81 70 - No P0.04 Ratio of inertia 250 0 ~ 10000 250 % No P0.05 Command pulse input selection 0 0 ~ 1 0 - No P0.06 Command pulse input selection 0 0 ~ 1 0 - No P0.07 Command pulse counts per o 0 0 ~ 32767 1 - No P0.08 Command pulse counts per one 2500 1 ~ 2500 2500 P/ev Power off valid P1.11 Output pulse counts per one 2500 1 ~ 2500 2500 P/ev Power off valid P0.114 Position deviation setup	Classify Select	Parameter N	ParameterName	Value	Range	Default	Units	Remark	
Add Custom Pr0.01 Control mode 20 20 ° 39 0 - Poweroff valid birstionSuppression Pr0.02 ReaHime auto-gain tuning mo 2 0 ° 2 0 - No Pr0.03 Selection of machine stiffness 70 50 ° 81 70 - No Pr0.04 Ratio of inertia 250 0 ° 10000 250 % No Pr0.05 Command pulse input selection 0 0 ° 1 0 - No Pr0.06 Command pulse input mode s 0 0 ° 1 0 - No Pr0.07 Command pulse input mode s 0 0 ° 3 3 - Power off valid Pr0.08 Command pulse counts per o 0 0 ° 32767 0 Pulse Power off valid Pr0.09 1st numerator of electronic gear 1 1 ° 32767 1 - No Pr0.10 Denominator of electronic gear 1 1 ° 32767 1 - No Pr0.11 Output pulse counts per o 0 0 ° 500 200 - No </td <td>asicSetting</td> <td>Pr0.00</td> <td>Mode loop gain</td> <td>1</td> <td>0 ~ 32767</td> <td>1</td> <td>0.1Hz</td> <td>No</td> <td></td>	asicSetting	Pr0.00	Mode loop gain	1	0 ~ 32767	1	0.1Hz	No	
Add Custom Pr0.02 Real-time auto-gain tuning mc 2 0 ~ 2 0 - No MontorSetting StatessionSetting StatessionSetting SectorySetting Selection of machine stiffness 70 50 ~ 81 70 - No Pr0.03 Selection of machine stiffness 70 50 ~ 81 70 - No StatessionSetting SectorySetting Pr0.04 Ratio of inertia 250 0 ~ 10000 250 % No Pr0.05 Command pulse input selection 0 0 ~ 1 0 - No Pr0.06 command pulse input mode s 0 0 ~ 3 3 - Power off valid Pr0.07 Command pulse counts per o 0 0 ~ 32767 0 Pulse Power off valid Pr0.08 Command pulse counts per o 0 0 ~ 32767 1 - No Pr0.10 Denominator of electronic gear 1 1 ~ 32767 1 - No Pr0.11 Output pulse counts per on m 2500 1 ~ 2500 2500 P/nev Power off valid Pr0.12 Reversion of pul	ainAdjustment	Pr0.01	Control mode	20	20~39	0	-	Power off valid	
electrory or queControl ionit or Setting special Setting provide and pulse input selection 70 50 ~ 81 70 - No extension Setting provide and pulse input selection 0 0 ~ 10000 250 % No extension Setting extension Setting Pr0.04 Ratio of inertia 250 0 ~ 10000 250 % No extension Setting Pr0.05 Command pulse input selection 0 0 ~ 1 0 - No extension Setting Pr0.06 command pulse input selection 0 0 ~ 1 0 - No Pr0.06 command pulse counts per on. 0 0 ~ 3 3 - Power off valid Pr0.07 Command pulse counts per on. 0 0 ~ 32767 0 Pulse Power off valid Pr0.09 1st numerator of electronic gear 1 1 ~ 32767 1 - No Pr0.10 Denominator of electronic gear 1 1 ~ 32767 1 - No Pr0.12 Reversal of pulse output/logic 0 0 ~ 10 0 - No - Pr0.13 1st torque limit	ibrationSuppression	Pr0.02	Real-time auto-gain tuning mo	2	0~2	0	-	No	
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ActorySetting Pr0.06 command pulse rotational dir 1 0 ~ 1 0 - Power off valid Pr0.07 Command pulse input mode s 0 0 ~ 3 3 - Power off valid Pr0.08 Command pulse courts per o 0 0 ~ 32767 0 Pulse Power off valid Pr0.09 1st numerator of electronic gear 1 1 ~ 32767 1 - No Pr0.10 Denominator of electronic gear 1 1 ~ 32767 1 - No Pr0.11 Output pulse courts per one m 2500 1 ~ 2500 2500 P/rev Power off valid Pr0.12 Reversal of pulse output logic 0 ~ 1 0 - No Pr0.13 1st torque limit 300 0 ~ 500 300 - No Pr0.16 Extend regenerative resistor 50 10 ~ 500 50 Q Power off valid Pr0.17 Regeneration discharge resistor 50 10 ~ 5000 50 Q Power off v	pecialSetting	Pr0.05	Command pulse input selection	0	0~1	0	-	No	
Pr0.07 Command pulse input mode s 0 0 ~ 3 3 - Power off valid Pr0.08 Command pulse counts per o 0 0 ~ 32767 0 Pulse Power off valid Pr0.09 1 strumerator of electronic gear 1 1 ~ 32767 1 - No Pr0.10 Denominator of electronic gear 1 1 ~ 32767 1 - No Pr0.10 Denominator of electronic gear 1 1 ~ 32767 1 - No Pr0.11 Output pulse counts per one m 2500 1 ~ 2500 2500 P/rev Power off valid Pr0.12 Reversal of pulse output logic 0 0 ~ 1 0 - No Pr0.13 1storque limit 300 0 ~ 500 300 - No Pr0.14 Position deviation setup 200 0 ~ 2 0 - No Pr0.15 Absolute encoder setup 0 0 ~ 200 50 Q Power off valid Pr0.16 Extenal regenerativ	actorySetting	Pr0.06	command pulse rotational dir	1	0~1	0	-	Power off valid	- 1
Add Custom Pr0.08 Command pulse counts per o 0 0 ~ 32767 0 Pulse Power off valid Pr0.09 1 st numerator of electronic gear 1 1 ~ 32767 1 - No Pr0.09 1 st numerator of electronic gear 1 1 ~ 32767 1 - No Pr0.10 Denominator of electronic gear 1 1 ~ 32767 1 - No Pr0.11 Output pulse counts per one m 2500 1 ~ 2500 2500 P/nev Power off valid Pr0.13 1 st torque limit 300 0 ~ 500 300 - No Pr0.14 Position deviation setup 200 0 ~ 500 200 0.1rev Encoder unit Pr0.15 Absolute encoder setup 0 0 ~ 2 0 - No Pr0.16 Extenal regenerative resistor 50 10 ~ 5000 50 Q Power off valid Pr0.17 Regeneration discharge resis 50 10 ~ 5000 50 Q Power off valid		Pr0.07	Command pulse input mode s	0	0~3	3	-	Power off valid	. 1
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Add Custom Pr0.10 Denominator of electronic gear 1 1 ~ 32767 1 - No Pr0.11 Output pulse counts per one m 2500 1 ~ 2500 2500 P/tev Power off valid Pr0.12 Reversal of pulse output logic 0 0 ~ 1 0 - Power off valid Pr0.13 1 storque limit 300 0 ~ 500 300 - No Pr0.14 Position deviation setup 200 0 ~ 500 200 0.1rev Encoder unit Pr0.15 Absolute encoder setup 0 0 ~ 2 0 - No Pr0.16 Extenal regenerative resistor 50 10 ~ 500 50 Q Power off valid Pr0.18 Vibration suppression -N after 0 0 ~ 1000 10 Pulse Encoder unit Pr0.18 Vibration suppression -N after 0 0 ~ 32767 0 - No Pr0.19 Microseismic inhibition 0 0 ~ 32767 0 - No Pr0.21 Reserved parameter 0 0 ~ 32767 0 - <td< td=""><td></td><td>Pr0.09</td><td>1st numerator of electronic gear</td><td>1</td><td>1~32767</td><td>1</td><td>-</td><td>No</td><td></td></td<>		Pr0.09	1st numerator of electronic gear	1	1~32767	1	-	No	
Add Custom Pr0.11 Output pulse counts per one m 2500 1 ~ 2500 2500 P/rev Power off valid Pr0.12 Reversal of pulse output logic 0 0 ~ 1 0 - Power off valid Pr0.13 1st torque limit 300 0 ~ 500 300 - No Pr0.14 Position deviation setup 200 0 ~ 500 200 0.1rev Encoder unit Pr0.15 Absolute encoder setup 0 0 ~ 2 0 - No Pr0.16 Extenal regenerative resistor 50 10 ~ 500 50 M Power off valid Pr0.17 Regeneration discharge resis 50 10 ~ 5000 50 W Power off valid Pr0.18 Vibration suppression - N after 0 0 ~ 1000 10 Pulse Encoder unit Pr0.19 Microseismic inhibition 0 0 ~ 32767 0 - No Pr0.20 Reserved parameter 0 0 ~ 32767 0 - No Pr0.21 Reserved parameter 0 0 ~ 32767 0 -		Pr0.10	Denominator of electronic gear	1	1~32767	1	-	No	
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Add Custom Pr0.22 Reserved parameter 0 0 ~ 32767 0 - No Add Custom Image: Custom Processing Control on Procesting Control on Procesting		Pr0.21	Reserved parameter	0	0~32767	0	-	No	
Add Custom Pr0.23 Reserved parameter 0 0 ~ 32767 0 - No		Pr0.22	Reserved parameter	0	0~32767	0	-	No	
Add Custom		Pr0.23	Reserved parameter	0	0~32767	0	-	No	
	Add Custom								_

5. Then click "save":

Leadshine ACHSeries (Offline) Communication Display Tools Language Help save Parameter Manage \times ParameterCompare 👸 ReadFile SaveAs Unload , Download Save Reset Help Parameter N. ParameterName Value Range Default Units Remark Classify Select Pr0.00 Mode loop dain 0 ~ 32767 0.1Hz No 1 BasicSetting 20~39 Pr0.01 20 Power off valid Control mode 0 _ GainAdjustment VibrationSuppression Pr0.02 Real-time auto-gain tuning mo... 2 0~2 0 _ No VelocityTorqueControl Pr0.03 Selection of machine stiffness ... 70 50~81 70 Nn _ MonitorSetting 250 % Pr0.04 Ratio of inertia 250 0~10000 No ExtensionSetting Pr0.05 Command pulse input selection 0 0~1 0 No SpecialSetting _ actorvSetting Pr0.06 command pulse rotational dir... 1 0~1 0 _ Power off valid 0~3 Pr0.07 Command pulse input mode s... 0 3 Power off valid _ Pr0.08 0~32767 Command pulse counts per o... 0 0 Pulse Power off valid Pr0.09 1st numerator of electronic gear 1 No 1~32767 1 _ Pr0.10 Denominator of electronic gear 1 1~32767 1 No Pr0.11 Output pulse counts per one m... 2500 1~2500 2500 Power off valid P/rev Pr0.12 Reversal of pulse output logic 0 0^{-1} 0 Power off valid Pr0.13 300 0~500 1st torque limit 300 No Pr0.14 Position deviation setup 200 0~500 200 0.1 rev Encoder unit Pr0.15 Absolute encoder setup Π 0~2 0 No. _ Pr0.16 Extenal regenerative resistor ... 50 $10 \sim 500$ 50 Ω Power off valid Pr0.17 Regeneration discharge resis... 50 10~5000 50 W Power off valid Pr0.18 0~1000 Vibration suppression - N after... Π 10 Pulse Encoder unit Pr0.19 10 Microseismic inhibition 0 0~1000 0.1Pulse Encoder unit Pr0.20 Reserved parameter 0 $0 \simeq 32767$ n. No Pr0.21 Reserved parameter Π 0~32767 n No _ Pr0.22 Reserved parameter 0 0~32767 Π No Pr0.23 Π No Reserved parameter 0~32767 Add Custom Þ • Description: 100%

6. Then the setting file of drive has been covered with this new lsr file, then pls restart the power, then the setting will be suitable for your application.